



BW-GNSS-DS

GNSS Displacement Sphere

Technical Manual

Product Introduction

BW-GNSS-DS is a GNSS displacement observation sphere with visual displacement monitoring and millimetre accuracy positioning launched by BWSENSING. Displacement observation ball adopts multi-system and multi-frequency RTK positioning technology and video AI perception technology fusion, simultaneously receiving five-star sixteen-frequency satellite positioning signals, with RTK dynamic and static observation modes, simultaneously measuring horizontal displacement and vertical displacement, built-in high-precision MEMS sensors, support remote video inspection, video linkage review. Low power consumption design, has a very high cost-effective, applied to universal ground disaster monitoring, water conservancy dam monitoring, landslide monitoring along roads and important buildings, hazardous mining reservoirs and dangerous houses monitoring and other scenes.

Specifications

| GNSS | |
|-----------------------------|---|
| Static accuracy | Planar $\pm (2.5 + 0.5 \times 10^{-6} \times D)$ mm, D is the baseline distance(unit: km) |
| | Vertical $\pm (5.0 + 0.5 \times 10^{-6} \times D)$ mm, D is the baseline distance(unit: km) |
| Differential data | RTCM2.x/3.x |
| Satellite support | GPS: L1, L1C, L2C, L2P, L5 |
| | BDS-2: B1I, B2I, B3I |
| | BDS-3: B1I, B3I, B1C, B2a, B2b* |
| | GLONASS: G1, G2 |
| | Galileo: E1, E5a, E5b |
| | QZSS: L1, L2C, L5 |
| | SBAS: L1 |
| | IRNSS: L5* |
| | L-band |
| Differential format support | CMR, RTCM2.X, RTCM3.X |
| Output format support | NMEA-1083, RTCM2.X, RTCM3.X |

| Basic Parameters | |
|---------------------------|-----------------------------------|
| Shutter | 1/1 s~1/30,000 s |
| Day/Night conversion mode | Auto ICR Colour to Black |
| Zoom | 4x optical zoom, 16x digital zoom |
| Slow shutter | Support |

| Video | |
|----------------------------|-------------------|
| Video compression standard | H.265/H.264/MJPEG |

| Fill Light | |
|------------------------------|---|
| Fill light type | Hybrid fill light |
| Fill light distance | 70 m infrared fill light, 30 m white light fill light |
| Anti-fill light overexposure | Support |
| Infrared wavelength range | 850 nm |

| Cloud Tower | |
|-----------------------------|--|
| Horizontal range | 0~340° |
| Vertical range | -10°~50° |
| Proportional zoom | Support |
| Number of presets | 300 |
| Preset point video freeze | Support |
| 3D Positioning | Support |
| Azimuth information display | Support |
| Timed tasks | Preset Points / Ball Restart / Ball Verification |
| Power failure memory | Support |

| Network | |
|---------------------|---|
| Interface protocols | Open API for software integration, open network video interface, ISAPI, Hikvision SDK, third-party management platform access, GB/T28181 protocol, ISUP, support for Fluorite access. |
| Security management | Authorised user name and password, and MAC address binding, HTTPS encryption, IEEE 802.1x network access control, IP address filtering. |
| Client | Support iVMS-4200 client |

Mobile Communication Parameters

| | |
|---------------------------|---------------------------------|
| Mobile communication type | 4G |
| SIM card | Mobile Unicom Telecom nano card |

Interfaces

| | |
|--------------------------|---|
| Network interface | RJ45 network port, adaptive 10 M/100 M network data |
| Audio | One way audio output |
| Alarm | One in one out |
| RS485 | one way |
| Restore factory settings | Support |

Image

| | |
|-------------------------------|---|
| Image parameter switching | Support |
| Image settings | Saturation, Brightness, Contrast, Sharpness |
| Day and night conversion mode | Day, night, automatic, timed switching |
| Wide dynamic | 120 dB ultra-wide dynamic |
| Signal-to-noise ratio | > 52 dB |
| Fog transmission support | Support |
| Image enhancement | Backlight compensation, glare suppression, 3D digital noise reduction |
| Area Focus | Support |
| Area Exposure | Support |

General Specification

| | |
|------------------------------------|---|
| Dimensions | 252.1 mm × 232.3 mm × 221.2 mm |
| Weight | 4.2 kg |
| Material | Corrosion-resistant material |
| Operating temperature and humidity | -40 °C~85 °C; humidity less than 95% |
| General features | Mirroring, password protection, watermarking technology, IP address filtering |
| Defogging | Support |

Deployment Programme

Yunfan Geological Hazard Monitoring Cloud Platform



Layout Design

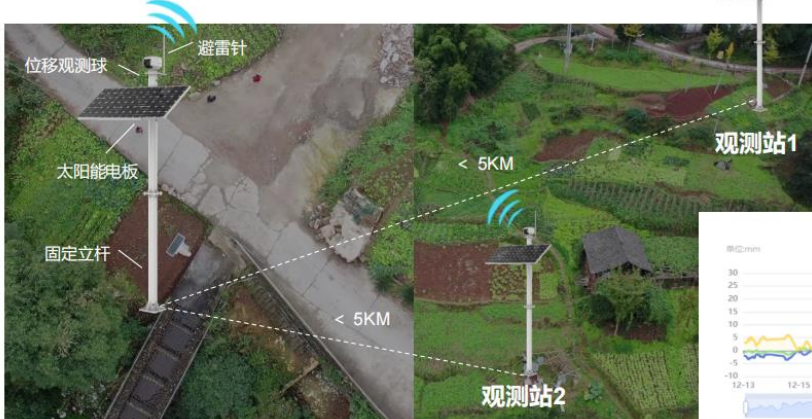
Unobstructed surroundings, datum station & observatory 1: N

基准站 1

选择基础坚实稳固，长期不会发生沉降、边坡移动的位置

观测站 N

选择需要监测有滑坡、沉降的位置



- GNSS安装环境周围无遮挡，有10°以上地平高度角的卫星通讯条件，特殊困难地区，可在一定范围（水平视角不超过60°）内，放宽至25°。
- GNSS基准站与观测站数量配比1: N，观测站距离基准站小于5KM



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- X方向 -4.024491
- Y方向 1.606807
- Z方向 5.155451

Installation instructions**1. Installation Base**

Digging a pit → Installing reinforced concrete beam → Cement curing

- ① Dig a 60*60*80cm pit at the equipment installation point.
- ② Fix the embedded parts of reinforced concrete beams of the uprights, pour concrete, and install the equipment uprights after solidification.

2. Equipment Installation

- ① Install the equipment on the top of the pole, use the fixed bracket, and install the solar panel.
- ② Organise the cables to be threaded from inside the riser, erect the riser, fix it to the pre-embedded reinforced concrete beam, and tighten the screws.

3. Equipment Power-up



- ① Power on the device, built-in ESIM card, the device automatically connects to the cloud server.

- ② Add device, mobile phone APP scanning device serial number to add to the platform.

GNSS Displacement sphere

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